## Waves on Strings

## OBJECTIVES

- to explore various properties of waves traveling along a Slinky
- to explore various properties of standing waves on a string


## EQUIPMENT

large Slinky
stopwatch
30-m measuring tape
spring scale
PASCO vibrator powered by the variable frequency function generator
string of a known linear density $\left(1.35 \times 10^{-4} \mathrm{~kg} / \mathrm{m}\right)$
set of masses from 50 g to 1000 g
50-g weight hanger
pulley
meter stick

## INTRODUCTION AND THEORY

Waves are one of the most important concepts in physics. They exist as waves on strings, sound in air and in solids, light, radio waves, microwaves, x-rays, and matter waves. Matter waves are the basis of the advanced field theory called quantum mechanics. All of these waves share much in common. A stretched string will be a very visual demonstration of wave phenomena in general.

In this lab we are going to study how waves travel on strings similar to the ones in many stringed musical instruments such as violin, guitar, and piano. In contrast to the sound waves which are longitudinal, waves on a string are transverse. This means that the displacement of the wave is perpendicular to its direction of propagation.


Figure 1

The speed of a transverse wave on a string is given by

$$
\begin{equation*}
\nu=\sqrt{\frac{T}{\rho}} \tag{1}
\end{equation*}
$$

where $T$ is the tension in the string measured in newtons $(N), \rho$ is the linear density of the string (or mass per unit length: $\rho=\frac{m}{l}$ ) measured in $\mathrm{kg} / \mathrm{m}$. It turns out that the velocities of all elastic waves have equations something like this

$$
\begin{equation*}
\sqrt{\frac{\text { "stiffness" }}{\text { "linear density" }}} . \tag{2}
\end{equation*}
$$

We can have two kinds of waves: traveling waves and standing waves. A standing wave develops when we have two waves with the same frequency traveling in opposite directions.

Waves on a string can be of any mathematical form. In many cases, waves will be excited by a simple harmonic oscillator, which will be of the form

$$
\begin{equation*}
x=x_{0} \cos (2 \pi f t) . \tag{3}
\end{equation*}
$$

These waves will propagate in a medium as waves with the same frequency, $f$, as the oscillator, and they will propagate as sine waves. They can be described in the mathematical form

$$
\begin{equation*}
y=y_{0} \sin 2 \pi\left(f t \pm \frac{x}{\lambda}\right) \tag{4}
\end{equation*}
$$

where $\lambda$ is the wavelength, and the "-" sign refers to the waves traveling to the $+x$ (right) direction and the " + " sign refers to the waves that travel in the $-x$ (left) direction. These waves will propagate with velocity

$$
\begin{equation*}
\nu=f \lambda \tag{5}
\end{equation*}
$$

By combining eqn. 1 and eqn. 5 we can describe the wavelength as

$$
\begin{equation*}
\lambda=\frac{1}{f} \sqrt{\frac{T}{\rho}} \tag{6}
\end{equation*}
$$

and since in this particular exercise $T=F_{g}=M g$, the expression for the wavelength becomes:

$$
\begin{equation*}
\lambda=\frac{1}{f} \sqrt{\frac{M g}{\rho}} . \tag{7}
\end{equation*}
$$

In the case we will study, the waves will be reflected back and forth by the end supports of the string, which will lead to the formation of standing waves with a pattern like the one shown in figure 2.


Figure 2: standing waves on a string with fixed endpoints

The places where the amplitude of vibrations is zero are called the nodes. The places where the amplitude is maximum are the anti-nodes (Fig. 2). The distance between the nodes will be one half of a wavelength. If the distance between the end supports of the string is $L$, a standing wave is possible only when the wavelength $\lambda$ satisfies the following relationship:

$$
\begin{equation*}
L=n\left(\frac{\lambda}{2}\right) \tag{8}
\end{equation*}
$$

where $n=1,2,3,4, \ldots$, and equals the number of anti-nodes.

## PROCEDURE

Please print the worksheet for this lab. You will need this sheet to record your data.

## Part A: Traveling waves on a Slinky

CAUTION: Handle the Slinky very carefully to avoid any possible permanent damage or distortion to the Slinky.

## Part A. 1

1 On the Lab 9 Worksheet, Part A, record the mass of the Slinky, which is given on the attached label.

2 The Slinky acts like a string for the purpose of propagation of transverse waves. Two lab partners should stretch the Slinky out to a length of about 20 ft in the hallway. The tile squares are $1 \mathrm{ft}^{2}$. Have the Slinky rest on the floor for much of its length.

3 One partner should launch a pulse, which will travel down the Slinky while the other partner measures the time it takes for the pulse to reach the opposite end. In order to get the hang of this, you will need to make several trials. Assess the average travel time from three good runs. Record it in the Lab 9 Worksheet, Table 1. You will need to find the uncertainty in time using the statistics function in GA.

4 Use the spring scale provided to measure the tension (in Newtons) in the Slinky.

## Part A. 2

1 Repeat steps 2-4 from Part A. 1 for the Slinky stretched to about 30 ft . Record the time from the three good runs on the Lab 9 Worksheet, Table 2.

Since the Slinky acts like a perfect spring, the time to propagate a wave down the Slinky will be about the same no matter what the length is. Another thing you should notice from this experiment is that the reflected pulse is inverted with respect to the incident pulse. This occurs because the end point is fixed and therefore can't move. You will need to mention these properties in your discussion.

In your Lab report, you will need to calculate the experimental speed of the Slinky and its uncertainty. (Hint: $v=L / t_{\text {ave }}$; where $L$ is the length of the stretched Slinky and $t_{\text {ave }}$ represents the average travel time.) Calculate the theoretical speed using eqn. 1.

## Part B: Standing waves on a string

The lab apparatus consists of a string, which is fixed on one end and attached to a weight hanger over a pulley on the other end as shown in fig. 3 .

The string is driven by a wave generator, which excites the string in a direction perpendicular to the string. The wave driver is like a loudspeaker without the cone that radiates sound. The wave driver is connected to a function generator/power amplifier. The function generator can put out a sine wave of variable frequency and variable amplitude.


Figure 3: the waves on a string setup

In fig. $3, L$ is the distance between the top of the pulley and the wave driver. Both of these points will be nodes.

## Part B.1. Constant Tension

1 Measure the length between the end supports of the string. Record it on the Lab 9 Worksheet.
2 Put the 200-g mass on the weight holder and tune the function generator to find the resonance condition (standing wave with maximum amplitude) for one anti-node.

3 Calculate the tension in the string. The mass of the weight holder is 50 g . (Hint: refer to the force diagram in figure 3.) Remember to include the mass of the weight holder.

4 On the Lab 9 Worksheet, Table 3, record the resonant frequency for $n=1$.
5 Now tune the function generator to higher frequencies and find resonant frequencies up to $n=$ 6.

6 In the Lab report, you will need to calculate the wave velocity for each case to check if it stays constant.

7 In GA, create two manual columns of 'frequency' and 'number of anti-nodes'. Record your data from the Lab 9 Worksheet. Plot the graph frequency $f$ vs. number of anti-nodes $n$. Apply linear fit to the graph. From the slope of the regression line, compute the experimental wave velocity and its uncertainty. Calculate the theoretical value of wave velocity based on eqn. 1. Compare the experimental and theoretical value of wave velocity in the string by finding the present difference.

8 Upload a file with your graphs. Do a print screen and save the graphs as a file with a maximum size of 1 MB . Print the graphs for your TA to sign, and for your reference.

## Part B.2. Constant Wavelength

Now you will make a series of measurements for $n=1$ varying the tension in the string.

1 Measure the length between the end supports of the string, in case it got changed. Record it on the Lab 9 Worksheet.

2 Place a $100-\mathrm{g}$ mass on the weight holder. Find the resonance frequency for $n=1$. Record it in the Lab 9 Worksheet, Table 4. Using masses in the range from 100 g to 1000 g (including the mass of the weight holder), vary the tension in the string. For each new value of tension find a resonance frequency for $n=1$. Keep recording data on the Lab 9 Worksheet, Table 4.

3 Create new manual columns in GA. Label them mass and frequency. Record your data from the Worksheet into GA. Create two calculated columns: Tension and square root of Tension Sqrt (Tension). Plot the graph frequency vs. Sqrt (Tension). Apply linear fit and record the slope and its uncertainty on the Lab 9 Worksheet.

4 Calculate the expected theoretical value of the slope that can be derived from eqn. 5 and eqn. 7. Compare it to the slope of the regression line by calculating the percent discrepancy.

5 Using the value of the slope, calculate the experimental value of the linear density of the string. Compare it to the theoretical value provided in the lab manual by calculating the percent discrepancy.

## Discussion Questions

Does the experiment support the theory stating that $\nu=\sqrt{\frac{T}{\rho}}$ ?

